

**Course Outline (W2026)**

**BME639: Control Systems and Bio-Robotics**

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| <b>Instructor(s)</b>                    | Dr. Owais Khan [Coordinator]<br>Office: ENG328<br>Phone: (416) 979-5000 x 556096<br>Email: owaiskhan@torontomu.ca<br>Office Hours:  |
| <b>Calendar Description</b>             | Introductory course for Biomedical Engineers: system modeling, simulation, analysis and classical-controller designs of linear, time-invariant, continuous time systems. System dynamic properties in time and frequency domains, performance specifications and basic properties of feedback are investigated. Stability analysis is reinforced through Routh-Hurwitz criterion, Root-Locus method, Bode plots, and Nyquist criteria. Concept of Bio-Robotics is introduced, and exposure to basics of state-space representation and feedback. Key control concepts are experienced through laboratory experiments using modular servo-system with open architecture, fully integrated with MATLAB and Simulink; use of simulation tools; and solving design problems.  |
| <b>Prerequisites</b>                    | BME 532, CEN 199  |
| <b>Antirequisites</b>                   | ELE 639   |
| <b>Corerequisites</b>                   | None  |
| <b>Compulsory Text(s):</b>              | <ol style="list-style-type: none"> <li>1. Automatic Control Systems, 10th Edition, Benjamin C. Kuo and Farid Golnaraghi, 2017, McGraw Hill Education</li> <li>2. BME639: Lecture Notes, The lecture notes are available on D2L course shell as PDF downloadable files.</li> <li>3. MATLAB User Manual (including Control Systems Toolbox and Simulink) the Mathworks, Inc., Copyright 1995-2018, available for download on the Departmental Network as Matlab help files.</li> </ol>  |
| <b>Reference Text(s):</b>               | <ol style="list-style-type: none"> <li>1. Control Systems Engineering, Norman S. Nise, 8th edition, 2019, Wiley Inc</li> <li>2. Modern Control Systems, Katsuhiko Ogata, 5th Edition, 2011, Prentice Hall</li> <li>3. Feedback Control of Dynamic Systems, 7th Edition, Gene F. Franklin, J. Da Powell, AbbasEmami-Naeini, 2014, Pearson</li> </ol>   |
| <b>Learning Objectives (Indicators)</b> | <p>At the end of this course, the successful student will be able to:</p> <ol style="list-style-type: none"> <li>1. Demonstrates understanding of control system representations, such as block diagrams, signal flow graphs, methods to analyze transient response. <b>(1c)</b></li> <li>2. Demonstrate understanding of stability analysis, such as root locus, Routh-Hurwitz criteria, Nyquist criterion, controller design (PD, PI, and PID) a, and state-space analysis. <b>(1d)</b></li> <li>3. Demonstrate competency in modeling and analysis of a SISO, continuous, LTI control system in a single feedback loop configuration, including specific tasks of defining a system analytical description, its stability and its dynamic response. <b>(2b)</b></li> <li>4. Determine transfer function model of the DC servo motor by applying two methods. First, the theoretical method, by applying the mathematical and scientific principles. Second, the experimental method, by using the real-time experimental data. Then compare the results</li> </ol> |

of the theory and the experiment and explain the behaviour of the process. This includes obtaining and verifying experimental data, assessing the accuracy of the results and explaining sources of possible discrepancies. **(3a)**

5. Implement a PI controller on the obtained model by simulation and on the real-time actual DC servo motor. Compare the control system results. Determine the existing constraints in the real-time control and explain their effects on the control systems. **(3b)**
6. Identify and then carry out steps required in designing a single loop controller (PID, Lead, Lag and State-feedback) for a low order LTI system to meet a set of specifications and then evaluate the controller design by verifying its performance against a set of criteria. **(4a)**
7. Identify and then carry out steps required in designing a simple in-the-loop controller (PID, Lead, Lag and State-feedback) for a low order LTI system to meet a set of specifications and then evaluate the controller design by verifying its performance against a set of criteria. **(4b)**
8. Demonstrate proficiency in the use of high-performance engineering modeling and analysis software (Matlab and Simulink) for control system analysis and design in this course, and for subsequent engineering practice. **(5a)**
9. Work effectively as a member of a team in the laboratory, manage the time to complete the lab projects appropriately in the given time schedule and submit the lab report according to the submission due date. Produce a lab summary individually and submit it with along the lab report to explain the teamwork has been done to achieve the goals of the lab project. **(6a)**
10. Produce a technical report using appropriate format, grammar, and citation styles, with figures and tables are carefully chosen to illustrate points made, with appropriate size, labels, and references in the body of the report, and respond appropriately to verbal questions from instructors - lab interviews. **(7a), (7b), (7c)**
11. Involve and play an active role in the lab projects, take a responsibility to complete the part of the lab project that has been assigned to do and produce a technical lab report for the assignment. **(8b)**

**NOTE:** Numbers in parentheses refer to the graduate attributes required by the Canadian Engineering Accreditation Board (CEAB).

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| <b>Course Organization</b> | 3.0 hours of lecture per week for 13 weeks<br>1.5 hours of lab per week for 12 weeks<br>0.0 hours of tutorial per week for 12 weeks |
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| <b>Teaching Assistants</b> | Ohiomuetti Uantioje (ouantioje@torontomu.ca)<br>Shayan Sepahvand (shayan.sepahvand@torontomu.ca)<br>Lucas Machowski (lucas.machowski@torontomu.ca) |
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| <b>Course Evaluation</b> | <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2" style="text-align: left;"><b>Theory</b></th> </tr> </thead> <tbody> <tr> <td style="width: 70%;">Midterm Exam</td> <td style="text-align: right;">34 %</td> </tr> <tr> <td>Final Exam</td> <td style="text-align: right;">45 %</td> </tr> <tr> <th colspan="2" style="text-align: left;"><b>Laboratory</b></th> </tr> <tr> <td>Lab 1</td> <td style="text-align: right;">7 %</td> </tr> <tr> <td>Lab 2</td> <td style="text-align: right;">7 %</td> </tr> <tr> <td>Lab 3</td> <td style="text-align: right;">7 %</td> </tr> <tr> <td><b>TOTAL:</b></td> <td style="text-align: right;"><b>100 %</b></td> </tr> </tbody> </table> | <b>Theory</b> |  | Midterm Exam | 34 % | Final Exam | 45 % | <b>Laboratory</b> |  | Lab 1 | 7 % | Lab 2 | 7 % | Lab 3 | 7 % | <b>TOTAL:</b> | <b>100 %</b> |
|--------------------------|--|---------------|--|--------------|------|------------|------|-------------------|--|-------|-----|-------|-----|-------|-----|---------------|--------------|
| <b>Theory</b>            |  |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| Midterm Exam             | 34 %   |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| Final Exam               | 45 %   |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| <b>Laboratory</b>        |  |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| Lab 1                    | 7 %  |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| Lab 2                    | 7 %  |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| Lab 3                    | 7 %  |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |
| <b>TOTAL:</b>            | <b>100 %</b>   |               |  |              |      |            |      |                   |  |       |     |       |     |       |     |               |              |

**Note:** In order for a student to pass a course, a minimum overall course mark of 50% must be obtained. In addition, for courses that have both "**Theory and Laboratory**" components, the student must pass the Laboratory and Theory portions separately by achieving a minimum of 50% in the combined Laboratory components and 50% in the combined Theory components. Please

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|                                     | refer to the <b>"Course Evaluation"</b> section above for details on the Theory and Laboratory components (if applicable).  |
| <b>Examinations</b>                 | Midterm exam in Week 7 during the Lecture time, two hours, problem solving, closed book (covers Week 1-6). Final exam during exam period, closed book (covers Weeks 1-13)   |
| <b>Other Evaluation Information</b> | There are assignment problems for each chapter posted on the course D2L. The assignment will not be collected. However, students are expected to solve the assignment problems. Lab marks are based on attendance, successful completion of pre-lab problems, participation, completion of experiment steps, lab reports and successful reply to your TA questions during submission. Students will have the responsibility to achieve a working knowledge of the software packages that will be used in the lab. Students will work in groups of two.  |
| <b>Other Information</b>            | <p>Course Policy on the Use of Generative AI:</p> <p>Where GenAI is prohibited entirely in the development of coursework:<br/>-----<br/>Use of Generative AI (e.g. ChatGPT, Grammarly, Perplexity, DeepL Translator) to develop or assist with any ideas or material submitted for coursework is expressly prohibited in this course. Use of Generative AI in this manner will be considered a breach of Policy 60.</p> <p>Where GenAI is permitted for grammar correction only:<br/>-----<br/>Students may use Generative AI (e.g. ChatGPT, Grammarly, Perplexity, DeepL Translator) only for minor grammar correction. This includes translating individual words and correcting spelling, punctuation and basic grammar issues. AI tools may not be used to make substantial revisions such as edits to style, tone, content nor rewrite phrases. Failure to stay within these limits will be considered a breach of Policy 60.</p> <p>Where GenAI is permitted for ideation and brainstorming:<br/>-----<br/>Students may use Generative AI (e.g. ChatGPT, Grammarly, Perplexity, DeepL Translator) for ideation and brainstorming but not for research or for writing anything that will be submitted for credit. Failure to stay within these limits will be considered a breach of Policy 60.</p> <p>Where GenAI is optional:<br/>-----<br/>Students may use Generative AI (e.g. ChatGPT, Grammarly, Perplexity, DeepL Translator) in this course. However,<br/>If you misrepresent source material (as AI often does), that will be considered a breach of Policy 60<br/>If your citations are not genuine (AI often makes up references), that will be considered a breach of Policy 60<br/>Students are required to write a clear declarative statement describing how AI tools were used and the extent of its contribution to the final submission.</p> <p>Where GenAI is integral:<br/>-----<br/>Students are required to use Generative AI in this course. If you have concerns about using this technology and require alternative assessments, by the end of the second week of class, consult with the instructor to make alternate arrangements.</p> <p>Questions? Contact:<br/>Academic Integrity Office, Toronto Metropolitan University<br/><a href="https://www.torontomu.ca/academicintegrity/">https://www.torontomu.ca/academicintegrity/</a><br/>aio@torontomu.ca Please note that these statements are merely examples of how instructors may want to frame their expectations around GenAI.</p> |

## Course Content

| Week | Hours | Chapters / Section     | Topic, description  |
|------|-------|------------------------|---|
| 1    | 3     | Chapter 1, 2, 3        | Introduction: Information session, General concepts of feedback and control systems, Closed-loop control versus Open-loop control, Modeling Mechanical and Electrical Systems, Differential Equations and Laplace Transform Review. |
| 2    | 3     | Chapter 4.1 - 4.2      | Transfer function representation, Block diagram rules and simplifications, Signal flow graphs Mason's Gain Formula.   |
| 3    | 3     | Chapter 7.1 - 7.5, 7.8 | Linear System Time Response: Transient response analysis, First-order systems, Second-order systems, Higher-order systems and dominant poles.   |
| 4    | 3     | Chapter 5, 7.6         | Stability Analysis: BIBO stability definition, Characteristic polynomials, Poles and stability conditions of LTI systems, Routh-Hurwitz stability criterion, Steady-State error analysis of feedback systems.                       |
| 5    | 3     | Chapter 9              | Root Locus Analysis: Closed-loop pole relation to the loop gain, Root locus graphical method of pole representation, Magnitude and angle laws, Root-locus plotting rules.   |
| 6    | 3     | Chapter 11.1 - 11.3    | Design of Control Systems in Time Domain for PD, PI and PID controllers.  |
|      |       |                        | ----- STUDY WEEK -----  |
| 7    | 3     |                        | Midterm Exam  |
| 8    | 3     | Chapter 10.1 - 10.2    | Frequency Response Analysis I: Frequency response, Frequency-domain representation, Bode Diagram, Relation between magnitude and phase, Cross over frequency Bandwidth.   |

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| 9  | 3 | Chapter 10.4 - 10.11              | Frequency Response Analysis: Polar Plots Nyquist Diagram Nyquist stability criteria Relative stability, Stability margins, Gain margin and phase margins   |
| 10 | 3 | Chapter 11.1 - 11.5               | Design of Controller in Frequency Domain: Lead/Lag compensator and P PI PD and PID controller design in frequency-domain   |
| 11 | 3 | Chapter 3.6 - 3.7, 4-3, 8.1- 8.11 | State-Space Analysis: State-space representation of systems, State diagrams and state variables, State-space equations from high-order differential equations, State transition matrix, Characteristic equation and eigenvalues. |
| 12 | 3 | Chapter 8.12 - 8.19               | State-Space Design: Controllability and Observability of Linear Systems, State feedback control, Tracking objectives, Pole placement method, State feedback with integral control  |
| 13 | 3 | Practice Problems                 | Course Review  |

### Laboratory(L)/Tutorials(T)/Activity(A) Schedule

| Week  | L/T/A   | Description  |
|-------|---------|--|
| 2-3   | Lab 1.1 | Lab # 1.1: Introduction to Simulink, Open-Loop Control vs. Closed-Loop Control     |
| 4-5   | Lab 1.2 | Lab # 1.2: Transient Response Analysis and Stability of 2nd and 3rd Order Systems. |
| 6-7   | Lab 2.1 | Lab # 2.1: Transfer Function Modeling of Physical Systems and Control.             |
| 8-9   | Lab 2.2 | Lab # 2.2: Introduction to Lead and Lag Compensators                               |
| 10-11 | Lab 3.1 | Lab # 3.1: Introduction to PI PD and PID Controllers                               |
| 12-13 | Lab 3.2 | Lab # 3.2: State Space Modeling of Physical Systems and Control.                   |

## University Policies & Important Information

Students are reminded that they are required to adhere to all relevant university policies found in their online course shell in D2L and/or on [the Senate website](#)

Refer to the [Departmental FAQ page](#) for further information on common questions.

## Important Resources Available at Toronto Metropolitan University

- [The University Libraries](#) provide research [workshops](#) and individual consultation appointments. There is a drop-in Research Help desk on the second floor of the library, and students can use the [Library's virtual research help service](#) to speak with a librarian, or [book an appointment](#) to meet in person or online.
- [Student Life and Learning Support](#) offers group-based and individual help with writing, math, study skills, and transition support, as well as [resources and checklists to support students as online learners](#).
- You can submit an [Academic Consideration Request](#) when an extenuating circumstance has occurred that has significantly impacted your ability to fulfill an academic requirement. You may always visit the [Senate website](#) and select the blue radio button on the top right hand side entitled: Academic Consideration Request (ACR) to submit this request.

*For Extenuating Circumstances, [Policy 167: Academic Consideration](#) allows for a once per semester ACR request without supporting documentation if the absence is less than 3 days in duration and is not for a final exam/final assessment. Absences more than 3 days in duration and those that involve a final exam/final assessment, always require documentation. Students must notify their faculty/contract lecturer once a request for academic consideration is submitted. See Senate [Policy 167: Academic Consideration](#).*

Longer absences are not addressed through Policy 167 and should be discussed with your Chair/Director/Program to be advised on next steps.

- [FAQs Academic Considerations and Appeals](#)
- Information on Copyright for [Faculty/Contract Lecturers](#) and [students](#).

## Lab Safety (if applicable)

Students are to strictly adhere and follow:

- a. The Lab Safety information/guidelines posted in the respective labs,
- b. provided in their respective lab handouts, and
- c. instructions provided by the Teaching Assistants/Course instructors/Technical Staff.

During the lab sessions, to avoid tripping hazards, the area around the lab stations should not be surrounded by bags, backpacks etc, students should place their bags, backpacks etc against the walls of the labs and/or away from their lab stations in such a way that it avoids tripping hazards.

## Accessibility

- Similar to an [accessibility statement](#), use this section to describe your commitment to making this course accessible to students with disabilities. Improving the accessibility of your course helps minimize the need for accommodation.
- Outline any technologies used in this course and any known accessibility features or barriers (if applicable).
- Describe how a student should contact you if they discover an accessibility barrier with any course materials or technologies.

## Academic Accommodation Support

Academic Accommodation Support (AAS) is the university's disability services office. AAS works directly with incoming and returning students looking for help with their academic accommodations. AAS works with any student who requires academic accommodation regardless of program or course load.

- Learn more about [Academic Accommodation Support](#).
- Learn [how to register with AAS](#).
- Learn about [Policy 159: Academic Accommodation of Students with Disabilities](#)

Academic Accommodations (for students with disabilities) and Academic Consideration (for students faced with extenuating circumstances that can include short-term health issues) are governed by two different university policies. Learn more about [Academic Accommodations versus Academic Consideration and how to access each](#).

## Wellbeing Support

At Toronto Metropolitan University, we recognize that things can come up throughout the term that may interfere with a student's ability to succeed in their coursework. These circumstances are outside of one's control and can have a serious impact on physical and mental well-being. Seeking help can be a challenge, especially in those times of crisis.

If you are experiencing a mental health crisis, please call 911 and go to the nearest hospital emergency room. You can also access these outside resources at anytime:

- **Distress Line:** 24/7 line for if you are in crisis, feeling suicidal or in need of emotional support (phone: 416-408-4357)
- **Good2Talk:** 24/7-hour line for postsecondary students (phone: 1-866-925-5454)
- **Keep.meSAFE:** 24/7 access to confidential support through counsellors via [My SSP app](#) or 1-844-451-9700

If non-crisis support is needed, you can access these campus resources:

- **Centre for Student Development and Counselling:** 416-979-5195 or email [csdc@torontomu.ca](mailto:csdc@torontomu.ca)
- **Consent Comes First - Office of Sexual Violence Support and Education:** 416-919-5000 ext 3596 or email [osvse@torontomu.ca](mailto:osvse@torontomu.ca)
- **Medical Centre:** call (416) 979-5070 to book an appointment

We encourage all Toronto Metropolitan University community members to access available resources to ensure support is reachable. You can find more resources available through the [Toronto Metropolitan University Mental Health and Wellbeing](#) website.